

#### STANDARD EQUIPMENT

- Engine, YANMAR 4TNV98CT, Diesel engine with turbocharger, EU Stage V compliant
- Auto Idle Stop
- Automatic engine deceleration
- Batteries (2 x 12 V 72 Ah)
- Starting motor (24 V 3.5 kW), 1.44 kW alternator
- Engine oil pan drain cock
- Double element air cleaner
- Refuelling pump
- Battery disconnect switch

#### CONTROL

- Working mode selector (H-mode, S-mode and ECO-mode)
- N&B piping (proportional hand controlled) (Not applicable for Offset boom)
- Object Handling Kit

#### **SWING SYSTEM & TRAVEL SYSTEM**

- Swing rebound prevention system
- Straight propel system
- Two-speed travel with automatic shift down
- Sealed & lubricated track links
- 450 mm steel shoes
- Grease-type track adjusters
- Automatic swing brake
- Dozer Blade

#### MIRRORS, LIGHTS & CAMERAS

- Rear view camera, left & right side view camera
- Three front working lights (LED)

#### **CAB & CONTROL**

- Two control levers, pilot-operated
- Horn, electric
- Integrated left-right slide-type control box
- LED door light (interior)
- Coat hook
- Large cup holder
- Detachable two-piece floor mat
- GRAMMER\* air suspension seat with heater
- Retractable seatbelt
- Headrest
- Handrails
- Intermittent Parallel wiper with double-spray washer
- Skylight
- Openable top guard (ISO 10262: 1998)
- Tinted safety glass
- Pull-type front window and removable lower
- Easy-to-read 10-inch LCD SCREEN multi-display monitor
- Emergency escape hammer
- 12 V converter
- Automatic air conditioner
- GEOSCAN

#### **OPTIONAL EQUIPMENT**

- Various optional arms
- Wide range of shoes
- Front-guard protective structure (may interfere with bucket action)
- Additional counterweight (+300 kg)
- Cab top work LED lights (two lights)
- Mechanical suspension seat
- Rain visor (may interfere with bucket action)
- Extra piping (proportional hand controlled)

- Long Stroke Dozer
- Offset boom
- Quick Hitch piping
- Heavier counterweight (+350 kg)
- Eagle eye view
- Lower Frame Guard
- Roll sun shade
- Travel alarm

Note: Standard and optional equipment may vary. Consult your KOBELCO dealer for specifics.

\*GRAMMER is trademark of GRAMMER AG. registered in Germany and other countries.

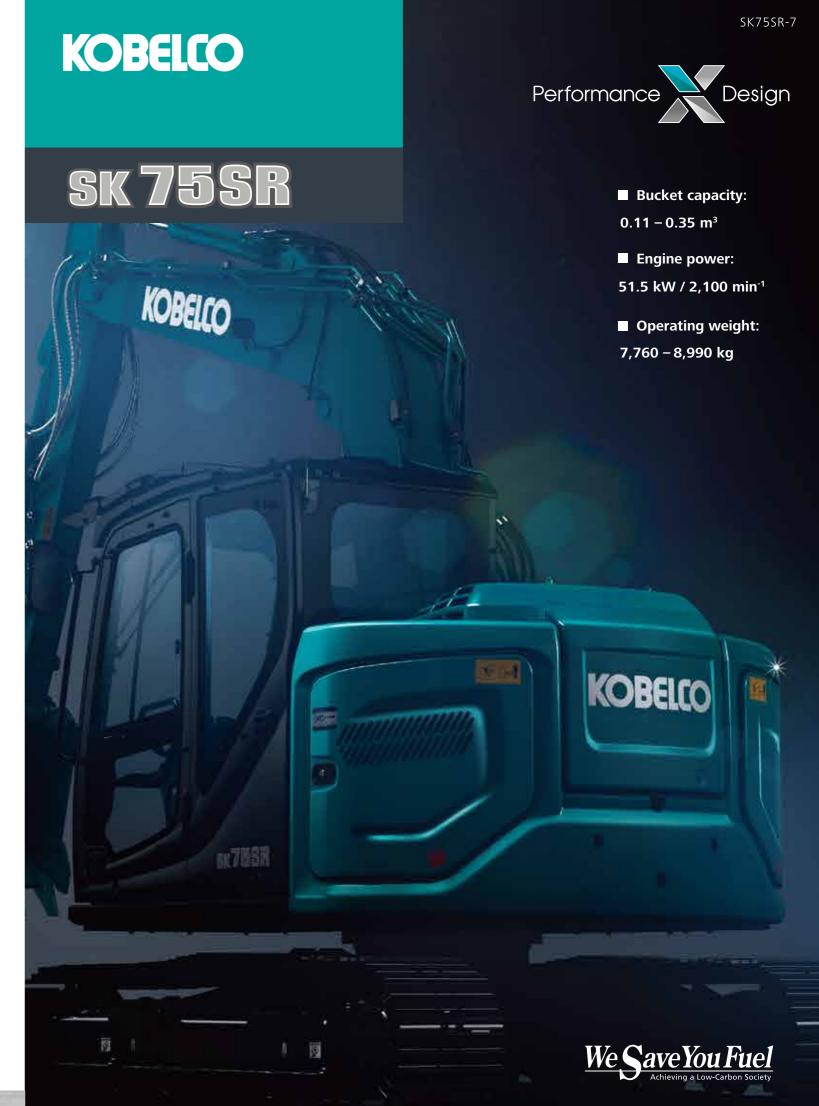
Note: This catalogue may contain attachments and optional equipment that are not available in your area. And it may contain photographs of machines with specifications that differ from those of machines sold in your areas. Please consult your nearest KOBELCO distributor for those items you require. Due to our policy of continuous product improvements all designs and specifications are subject to change without advance notice. Copyright by **KOBELCO CONSTRUCTION MACHINERY CO., LTD.** No part of this catalogue may be reproduced in any manner without notice.

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# UNFORGETTABLE COMFORT

### **1** Air suspension seat with heating

A GRAMMER\* seat is installed as standard equipment, which achieves excellent shock absorption and superior ride comfort.

\*GRAMMER is trademark of GRAMMER AG. registered in Germany and other countries.

### ② Air-conditioner blowing from the rear

Air is blown against the operator's waist and the back of their head, offering more comfortable operation.

## **Solution** Lever angles allow for comfortable operations

The operator can move the levers horizontally without twisting their wrist, which reduces the fatigue caused by the operations.



### 4 LED door light

The LED interior light automatically turns on when the door is opened or when the ignition is set to OFF.

This ensures easy entry and exit at nighttime.

**9** Parallel wipers secure a wide field of view







### A WIDER VIEW BRINGS A WIDER RANGE OF USE

#### 10-inch colour monitor (the largest in the industry)

The easy-to-operate menu screen facilitates reading of important information. Images from the built-in cameras can be checked on the large screen, which helps secure safety. In addition, each icon has become easy to recognise. A password is required when starting the engine for greater security.



The right camera and rear camera (right side view mode)



The right camera and rear camera (straight view mode)





#### Right and rear cameras

Images from the right camera and rear camera are displayed together on the large colour monitor. The right camera view can be selected between the straight view mode and right side view mode. In addition, the bird's-eye view mode can also be selected. As an optional setting, the eagle eye view mode can also be selected.





## Screen display linked with the jog dial operation

The jog dial can be operated as desired without causing stress. Turn the jog dial to the right or left to select an item and press the dial to confirm the selection.



### **GREATER MULTI-FUNCTION CAPABILITIES**

#### **Attachment mode**

The flow-rate modes of the bucket, breaker, nibbler, and rotating grapple are set before delivery, which allows you to start operating immediately. Mode settings for other attachments, such as the tilt rotator, can easily be added or changed.



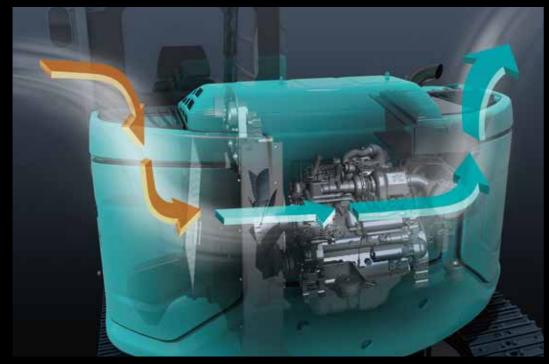


### **TYPES OF ATTACHMENT MODE**

	TYPE	MODE	OBJECTIVE OF MODE
	1	Bucket	Balance in operations such as levelling can be adjusted.
CURRENT MODE		Breaker	Arm regeneration function considering front attachment weight is provided beforehand.
	A	Nibbler (crusher)	Change of arm speed due to nibbler (crusher) opening/closing is reduced.

	TYPE	MODE	OBJECTIVE OF MODE
	8	Rotating grapple	Swing operation on slope while raising attachment/ equipment becomes possible. Boom 2-speed systems is controlled by proportional valve.
NEWLY	4	Processor	N&B flow rate is set to maximum specifically. Regeneration of arm in operation while using front attachment is changed.
ADDED MODE	6	Thumb bucket	Swing operation while raising attachment/equipment and opening thumb bucket becomes possible.
	4	Tilt rotator	When combined operation with arm is performed, hydraulic interference is prevented.
		Spare mode for custom setting	This mode should be customized at each field. This is provided for front attachment other than those described above.

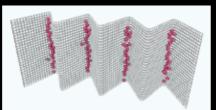
### **NON-STOP OPERATION BY IND**





#### **iNDr Filter**

A high-density mesh filter blocks dust intruding during air intake. This prevents the cooling device and the air cleaner from clogging with dust and maintains their performances. The ridges of the corrugated filter allow the air to pass through, and the grooves collect the dust, which prevents the filter from clogging.



How the filter catches dust



Maintainable on the ground Portions that require daily maintenance, such as lubrication, have been laid out in easily accessible locations.



**Easily removable bonnet** The bonnet can be detached by removing only the bolts, allowing easy access to the inside.

### **CONVENIENT AND SENSIBLE EQUIPMENT**



**Engine start password** A password is required when starting the engine for greater security. The initial password must be set at our workshop.



Wiper adjustment function In addition to the intermittent wiper mode and continuous wiper mode, the one-time wiper mode was added.



Parallel wipers/Sun screen



The console-integrated seat allows for comfortable operation.



12 V power supply



**Smartphone holder** 



Built-in rear camera/right camera



**Openable FOPS guard** The openable guard allows for easy



Wide clearance between the upper body and the shoes



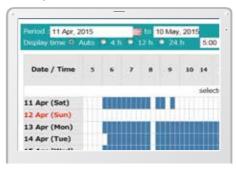


## **Ecavator Remote Monitoring System**



### **Operating Hours**

- •A comparison of operating times of machines at multiple locations shows which locations are busier and more profitable.
- ·Operating hours on site can be accurately recorded, for running time calculations needed for rental machines, etc.

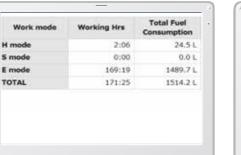


#### **Fuel Consumption Data**

•Data on fuel consumption and idling times can be used to indicate improvements in fuel consumption.

#### **Graph of Work Content**

•The graph shows how working hours are divided among different operating categories, including digging, idling, travelling and optional operations.



Fuel consumption



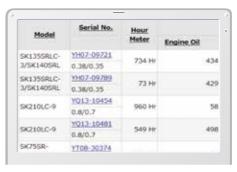
Work status

**Warning Alerts** 

#### **Maintenance Data and Warning Alerts**

#### **Machine Maintenance** Data

- Provides maintenance status of separate machines operating at multiple sites.
- Maintenance data is also relayed to KOBELCO service personnel, for more efficient planning of periodic servicing.



•This system warns an alert if an anomaly is sensed, preventing damage that could result in machine

#### **Alarm Information Can Be Received through E-mail**

· Alarm information or maintenance notice can be received through E-mail, using a computer or cell phone.



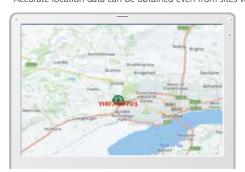
#### **Daily/Monthly Reports**

•Operational data downloaded onto a computer helps in formulating daily and monthly reports.

#### **Direct Access to Operational Status**

#### **Location Data**

• Accurate location data can be obtained even from sites where communications are difficult.





Piccod 11 Apr. 2015	10 May, 2015	Search	
Type of Operation	Working Hrs.		Ratio
Total Working Hrs		\$69 Hrs	100 %
Digging Hrs	100	72.2 Hrs	43 %
Traveling Hrs		18.3 Hrs.	119
Idle Hrs		15.9 Hrs	9.5
Opt Att Hrs	- No. 10	62.5 Hrs	37 9
Crane Mode Hrs		0 Hrs.	0.9

Work data

**Engine Start** Alarm

**Security System** 

•The system can be set an alarm if the machine is operated outside designated time.



Engine start alarm outside prescribed work time

Alarm messages can be received on mobile device.

#### **Area Alarm**

•It can be set an alarm if the machine is moved out of its designated area to another location.



Alarm for outside of reset area

### **Specifications**



Model	YANMAR 4TNV98CT
Туре	Four-stroke, liquid-cooled, direct injection diesel, turbo charged complies with EU Stage V exhaust emission regulation
No. of cylinders	4
Bore and stroke	98 mm x 110 mm
Displacement	3.318 L
Rated power output	51.5 kW/2,100 min <sup>-1</sup> (ISO 9249: with fan) 53.7 kW/2,100 min <sup>-1</sup> (ISO 14396: without fan)
Max. torque	289 N.m/1,365 min <sup>-1</sup> (ISO 9249: with fan) 296 N.m/1,365 min <sup>-1</sup> (ISO 14396: without fan)

## **Hydraulic system**

Pump		
Туре	Double variable displacement axial piston pump + one gear pump	
Max. discharge flow	2 x 72.5 L/min 1 x 19 L/min	
Relief valve setting		
Boom, arm and bucket	29.4 MPa {300 kgf/cm²}	
Travel circuit	29.4 MPa {300 kgf/cm²}	
Swing circuit	24.5 MPa {250 kgf/cm²}	
Control circuit	5.0 MPa {50 kgf/cm²}	
Pilot control pump	Gear type	
Main control valves	12-spool	
Oil cooler	Air cooled type	

### Swing system

Swing motor	One fixed displacement piston motor
Brake	Hydraulic; locking automatically when the swing control lever is in the neutral position
Parking brake	Wet multiple plate
Swing speed	11.5 min <sup>-1</sup>
Tail swing radius	1,380 mm
Swing torque	17 kN·m

### Travel system

Travel motors	Variable displacement piston, two-speed motors
Travel brakes	Hydraulic brake
Parking brakes	Wet multiple plate
Travel shoes	39 each side
Travel speed	5.0/2.7 km/h
Drawbar pulling force	77.3 kN (SAE)
Gradeability	58% {30°}

### **Cab & control**

Cab		
All-weather, sound-suppressed steel cab mounted on the silicon-sealed viscous mounts and equipped with a heavy, insulated floor mat		
Control		
Two hand levers and two foot pedals for travel		
Two hand levers for excavating and swing		
Electric rotary-type engine throttle		

Noise levels	
External	98 dB(A) (2000/14/EC)
Operator	73 dB(A) (ISO 6396)

### Boom, arm & bucket

Boom cylinders	110 mm x 916 mm
Arm cylinder	95 mm x 839 mm
Bucket cylinder	85 mm x 762 mm

### **Dozer blade**

Dozer cylinder	135 mm x 129 mm
Dimension	2,300 mm (for 450 mm shoe) (width) x 460 mm (height)*
Working range	360 mm (up) x 250 mm (down)

<sup>\*</sup>Dozer width is changed according to the shoe width difference.

### Refilling capacities & lubrications

Fuel tank	120 L	
Cooling system	12.8 L	
Engine oil	11.8 L	
Travel reduction gear	2 x 1.3 L	
Swing reduction gear	1.5 L	
Hudraulic oil tank	44 L tank oil level	
Hydraulic oil tank	84 L hydraulic system	

## Attachments

Backhoe bucket and combination (Reference only)

	Use				Backho	e bucket				
	Use		Standard	Standard Narrow						
Duelot some situ	ISO heaped	m³	0.28	0.11	0.14	0.18	0.22	0.35		
Bucket capacity	Struck	m³	0.21	0.09	0.12	0.14	0.18	0.26		
Omanian width	With side cutter	mm	750	-	480	550	650	870		
Opening width	Without side cutter	mm	680	400	410	480	580	800		
No. of teeth			4	3	3	3	4	4		
Bucket weight		kg	210	160	170	180	200	230		
Combination	1.71 m arm		0	0	0	0	0	Δ		
Combination	2.13 m arm		Δ	0	0	0	0	×		

#### $\bigcirc$ Standard $\bigcirc$ Recommended $\triangle$ Loading only $\times$ Not recommended

### **Working ranges**

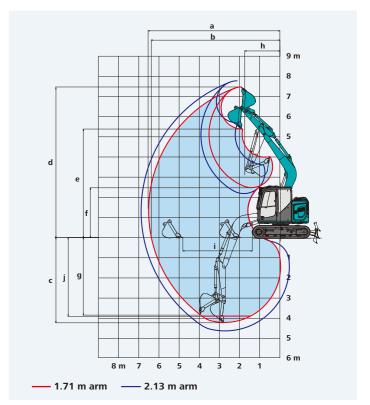
		Unit: m
Boom		.82 m
Arm Range	1.71 m	2.13 m
a-Max. digging reach	6.48	6.88
b-Max. digging reach at ground level	6.35	6.76
c- Max. digging depth	4.16	4.58
d-Max. digging height	7.41	7.75
e-Max. dumping clearance	5.34	5.67
f- Min. dumping clearance	2.46	2.19
g-Max. vertical wall digging depth	3.73	4.14
h-Min. swing radius	1.73	2.13
i- Horizontal digging stroke at ground level	2.83	3.21
j- Digging depth for 2.4 m (8') flat bottom	3.83	4.31
Bucket capacity ISO heaped m <sup>3</sup>	0.28	0.22

#### Digging force (ISO 6015)

		UIII. KIN
Arm length	1.71 m	2.13 m
Bucket digging force	60	.3
Arm crowding force	39.3	35.2

### **Dimensions**

A	rm length	1.71 m	2.13 m*
Α	Overall length	5,840 6,550* **	6,370 6,570**
В	Overall height (to top of boom)	2,560	2,540
C	Overall width	2,30	0***
D	Overall height (to top of cab)	2,5	70
Ε	Ground clearance of rear end****	72	20
F	Ground clearance****	32	20



Unit: mm

G Tail swing radius (add on counter weight) 1,380 (1,470)

G' Distance from centre of swing to rear end 1,380

H Tumbler distance 2,210

I Overall length of crawler 2,830

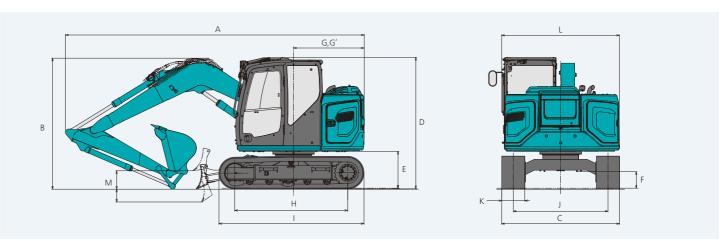
J Track gauge 1,850

K Shoe 450

L Overall width of upperstructure 2,300

M Dozer blade (up/down) 360/250 500/500\*\*

\* Dozer blade facing backward \*\*Long Stroke Dozer \*\*\* 450 mm shoe \*\*\*\* Without including height of shoe lug

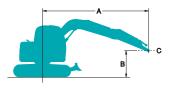


### **Operating weight & ground pressure**

In standard trim, with standard boom, 1.71 m arm, and 0.28 m<sup>3</sup> ISO heaped bucket

Shaped		Triple grouser sh	oes (even height)	Rubber pad shoes	Rubber shoes	BS Geogrip shoes
Shoe width	mm	450	600	450	450	450
Overall width of crawler	mm	2,300	2,450	2,300	2,300	2,300
Ground pressure	kPa	35	27	37	35	36
Operating weight	kg	7,940	8,190	8,260	7,760	7,980

### **Lift capacities**





A: Reach from swing centreline to arm top B: Arm top height above/below ground C: Lift point

Bucket: Without bucket
Relief valve setting: 29.4 MPa {300 kgf/cm²}

SK75SR		Arm: 1.71 m	Bucket: Withou	t Counterweigh	t: 700 kg Shoe:	450 mm Dozer	: Blade up			
	А	1.5 m		3.0	) m	4.5	m	At max	c. reach	
В		<u> </u>	-	<u> </u>	-	-	<b>—</b>	<u> </u>	-	Radius
6.0 m	kg							*2,350	*2,350	2.74 m
4.5 m	kg			*2,410	*2,410			1,780	1,530	4.42 m
3.0 m	kg			*2,920	2,760	1,690	1,450	1,330	1,150	5.18 m
1.5 m	kg			2,990	2,460	1,600	1,360	1,190	1,020	5.44 m
G.L.	kg			2,830	2,320	1,530	1,300	1,220	1,040	5.27 m
–1.5 m	kg	*3,840	*3,840	2,830	2,310	1,530	1,290	1,470	1,250	4.63 m
–3.0 m	kg			*1,330	*1,330			*1,140	*1,140	3.23 m

SK75SR		Arm: 1.71 m	Bucket: Without	t Counterweigh	t: 700 kg + 300	kg Shoe: 450 n	nm Dozer: Blad	e up		
	А	1.5	m	3.0	) m	4.5	m	At max	. reach	
		4	<b>—</b>	4	<b>—</b>	4	<b>—</b>	4	<b>—</b>	Radius
6.0 m	kg							*2,350	*2,350	2.74 m
4.5 m	kg			*2,410	*2,410			*1,850	1,680	4.42 m
3.0 m	kg			*2,920	*2,920	1,860	1,600	1,470	1,270	5.18 m
1.5 m	kg			3,300	2,730	1,770	1,510	1,330	1,140	5.44 m
G.L.	kg			3,140	2,580	1,700	1,450	1,360	1,170	5.27 m
–1.5 m	kg	*3,840	*3,840	*2,960	2,580	1,700	1,450	1,630	1,390	4.63 m
−3.0 m	kg			*1,330	*1,330			*1,140	*1,140	3.23 m

SK75SR		Arm: 1.71 m	Bucket: Withou	t Counterweigh	t: 1,050 kg Sho	e: 450 mm Doz	er: Blade up			
	А	1.!	5 m	3.0	) m	4.5	5 m	At max	c. reach	
		<u> </u>	<del></del>	<u> </u>	<b>—</b>	<u> </u>	<b>—</b>	<u> </u>	<b>—</b>	Radius
6.0 m	kg							*2,350	*2,350	2.74 m
4.5 m	kg			*2,410	*2,410			*1,850	1,690	4.42 m
3.0 m	kg			*2,920	*2,920	1,870	1,610	1,480	1,280	5.18 m
1.5 m	kg			3,320	2,740	1,780	1,520	1,340	1,150	5.44 m
G.L.	kg			3,160	2,600	1,710	1,460	1,370	1,170	5.27 m
–1.5 m	kg	*3,840	*3,840	*2,960	2,590	1,710	1,450	1,640	1,400	4.63 m
–3.0 m	kg			*1,330	*1,330			*1,140	*1,140	3.23 m

SK75SR		Arm: 2.13 m	Arm: 2.13 m Bucket: Without Counterweight: 700 kg Shoe: 450 mm Dozer: Blade up											
	А	1.5	i m	3.0	) m	4.5	i m	At max	. reach					
В		<u> </u>	<b>—</b>	4	<b>—</b>	Image: Control of the	<b>—</b>	<u> </u>	<b>—</b>	Radius				
6.0 m	kg			*2,240	*2,240			*1,920	*1,920	3.48 m				
4.5 m	kg			*2,120	*2,120	1,750	1,510	1,490	1,290	4.90 m				
3.0 m	kg			*2,630	*2,630	1,700	1,460	1,170	1,000	5.60 m				
1.5 m	kg			3,030	2,500	1,590	1,360	1,050	900	5.84 m				
G.L.	kg			2,810	2,290	1,510	1,270	1,070	910	5.68 m				
–1.5 m	kg	*3,240	*3,240	2,770	2,250	1,480	1,250	1,250	1,060	5.09 m				
–3.0 m	kg	*2,690	*2,690	*1,930	*1,930			*1,300	*1,300	3.87 m				



SK75S	R	Arm: 2.13 m	Bucket: Withou	t Counterweigh	t: 700 kg + 300	kg Shoe: 450 n	nm Dozer: Blad	e up		
	А	1.5	5 m	3.0	) m	4.5	m	At max	c. reach	
		<b>₽</b>	<del></del>	1	<del></del>	Ţ	<del></del>			Radius
6.0 m	kg			*2,240	*2,240			*1,920	*1,920	3.48 m
4.5 m	kg			*2,120	*2,120	1,920	1,660	*1,600	1,420	4.90 m
3.0 m	kg			*2,630	*2,630	1,870	1,610	1,290	1,120	5.60 m
1.5 m	kg			3,340	2,760	1,760	1,510	1,180	1,010	5.84 m
G.L.	kg			3,120	2,560	1,680	1,420	1,190	1,020	5.68 m
–1.5 m	kg	*3,240	*3,240	3,080	2,520	1,650	1,400	1,390	1,190	5.09 m
–3.0 m	kg	*2,690	*2,690	*1,930	*1,930			*1,300	*1,300	3.87 m

SK75SR		Arm: 2.13 m Bucket: Without Counterweight: 1,050 kg Shoe: 450 mm Dozer: Blade up											
	А	1.5	i m	3.0	) m	4.5	m	At max	c. reach				
		<u> </u>	<b>—</b>	<u> </u>	<del></del>	-	<b>—</b>	<u> </u>	<b>—</b>	Radius			
6.0 m	kg			*2,240	*2,240			*1,920	*1,920	3.48 m			
4.5 m	kg			*2,120	*2,120	*1,930	1,670	*1,600	1,430	4.90 m			
3.0 m	kg			*2,630	*2,630	1,880	1,620	1,300	1,120	5.60 m			
1.5 m	kg			3,360	2,770	1,770	1,520	1,180	1,020	5.84 m			
G.L.	kg			3,140	2,570	1,690	1,430	1,200	1,030	5.68 m			
–1.5 m	kg	*3,240	*3,240	3,100	2,530	1,660	1,410	1,400	1,190	5.09 m			
-3.0 m	kg	*2,690	*2,690	*1,930	*1,930			*1,300	*1,300	3.87 m			

SK75SR		Arm: 2.13 m	Bucket: Without	t Counterweigh	Counterweight: 1,050 kg + 300 kg Shoe: 450 mm Dozer: Blade up							
	А	1.5	5 m	3.0	) m	4.5	m	At max	c. reach			
В		Ī	<b>—</b>	<u> </u>	<b>#</b>	Ŧ	<b>#</b>	<u> </u>	<b>—</b>	Radius		
6.0 m	kg			*2,240	*2,240			*1,920	*1,920	3.48 m		
4.5 m	kg			*2,120	*2,120	*1,930	1,820	*1,600	1,570	4.90 m		
3.0 m	kg			*2,630	*2,630	*2,050	1,770	1,430	1,240	5.60 m		
1.5 m	kg			*3,390	3,040	1,950	1,670	1,310	1,130	5.84 m		
G.L.	kg			3,450	2,830	1,860	1,580	1,330	1,140	5.68 m		
–1.5 m	kg	*3,240	*3,240	*3,170	2,790	1,830	1,560	1,540	1,320	5.09 m		
-3.0 m	kg	*2,690	*2,690	*1,930	*1,930			*1,300	*1,300	3.87 m		

- 1. Do not attempt to lift or hold any load that is greater than these lift capacities at their specified lift point radius and heights. Weight of all accessories must be deducted from the above lift capacities.
- 2. Lift capacities are based on machine standing on level, firm, and uniform ground. User must make allowance for job conditions such as soft or uneven ground, out of level conditions, side loads, sudden stopping of loads, hazardous conditions, experience of personnel, etc.
- Arm top defined as lift point.
- 4. The above lift capacities are in compliance with ISO 10567. They do not exceed 87% of hydraulic lift capacity or 75% of tipping load. lift capacities marked with an asterisk (\*) are limited by hydraulic capacity rather than tipping load.
- 5. Operator should be fully acquainted with the Operator's and Maintenance Instructions before operating this machine. Rules for safe operation of equipment should be adhered to at all times.
- 6. Lift capacities apply to only machine as originally manufactured and normally equipped by KOBELCO CONSTRUCTION MACHINERY CO., LTD.

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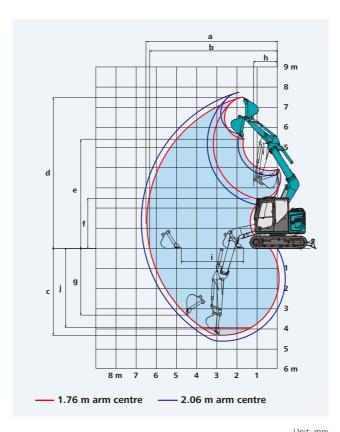
### **Offset boom specifications**

### **Working ranges**

Boom			3.8	2 m		
Arm		1.76 m			2.06 m	
Range	Max. left	Centre	Max. right	Max. left	Centre	Max. right
a-Max. digging reach	6.11	6.48	5.78	6.39	6.75	6.05
b-Max. digging reach at ground level	5.97	6.34	5.62	6.25	6.62	5.90
c- Max. digging depth	3.94	4.30	3.60	4.24	4.60	3.90
d-Max. digging height	7.17	7.49	6.88	7.40	7.72	7.11
e-Max. dumping clearance	5.11	5.43	4.81	5.34	5.66	5.04
f- Min. dumping clearance	2.13	2.45	1.83	1.85	2.17	1.55
g-Max. vertical wall digging depth	2.96	3.30	2.64	3.27	3.61	2.95
h-Min. swing radius	1.49	1.21	2.04	1.49	1.31	2.04
i- Horizontal digging stroke at ground level	3.10	3.08	3.09	3.61	3.59	3.64
j- Digging depth for 2.4 m (8') flat bottom	3.55	3.92	3.21	3.89	4.26	3.55
Bucket capacity ISO heaped m <sup>3</sup>	0.28	0.28	0.28	0.22	0.22	0.22

#### Digging force (ISO 6015)

		OTILL KIN
Arm length	1.76 m	2.06 m
Bucket digging force	60	.1
Arm crowding force	39.9	35.8

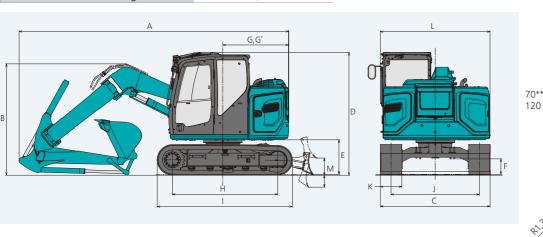


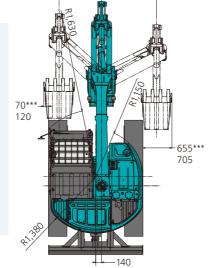
### **Dimensions**

Aı	rm length	1.76 m	2.06 m
Α	Overall length	6,170	6,210
В	Overall height (to top of boom)	2,330	2,410
C	Overall width	2,3	00*
D	Overall height (to top of cab)	2,5	70
Ε	Ground clearance of rear end**	72	20
F	Ground clearance**	32	20
G	Tail swing radius (add on counter weight)	1,380	(1,470)
G'	Distance from centre of swing to rear end	1,3	80

		01111.
Н	Tumbler distance	2,210
1	Overall length of crawler	2,830
J	Track gauge	1,850
K	Shoe width	450
L	Overall width of upperstructure	2,300
M	Dozer blade (up/down)	360/250

\*450 mm shoe \*\*Without including height of shoe lug





\*\*\*For 0.22 m3 bucket

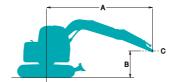
### **Operating weight & ground pressure**

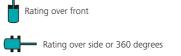
In standard trim, with standard boom, 1.76 m arm, and 0.28 m<sup>3</sup> ISO heaped bucket

Shaped		Triple grouser sh	oes (even height)	Rubber pad shoes	Rubber shoes	BS Geogrip shoes
Shoe width	mm	450	600	450	450	450
Overall width of crawler	mm	2,300	2,450	2,300	2,300	2,300
Ground pressure	kPa	39	30	40	38	39
Operating weight	kg	8,670	8,920	8,990	8,490	8,710

### Offset boom lift capacities







A: Reach from swing centreline to arm top B: Arm top height above/below ground C: Lift point Bucket: Without bucket

Relief valve setting: 29.4 MPa {300 kgf/cm²}

SK75SR		Arm: 1.76 m Bucket: Without Counterweight: 1,050 kg Shoe: 450 mm Dozer: Blade up									
В		1.5	m	3.0	) m	4.5 m		At max. reach			
			<del>#</del>		<del></del>	1	<del>#</del>		<del></del>	Radius	
6.0 m	kg							*2,710	*2,710	2.73 m	
4.5 m	kg			*2,460	*2,460			1,920	1,630	4.41 m	
3.0 m	kg			*2,960	*2,960	1,780	1,510	1,380	1,160	5.17 m	
1.5 m	kg			3,060	2,470	1,630	1,360	1,190	1,000	5.43 m	
G.L.	kg			2,790	2,230	1,510	1,250	1,200	1,000	5.27 m	
–1.5 m	kg	*3,750	*3,750	2,780	2,210	1,490	1,230	1,440	1,190	4.62 m	
-3.0 m	kg			*1,460	*1,460			*1,320	*1,320	3.22 m	

SK75SR	t .	Arm: 1.76 m	m Bucket: Without Counterweight: 1,050 kg + 300 kg Shoe: 450 mm Dozer: Blade up							
	А	1.5 m		3.0	3.0 m		4.5 m		At max. reach	
В		1	<del></del>	1	<del></del>	1	<del></del>	1	<b>—</b>	Radius
6.0 m	kg							*2,710	*2,710	2.73 m
4.5 m	kg			*2,460	*2,460			2,090	1,780	4.41 m
3.0 m	kg			*2,960	*2,960	1,950	1,660	1,520	1,290	5.17 m
1.5 m	kg			3,370	2,740	1,800	1,510	1,330	1,120	5.43 m
G.L.	kg			3,100	2,490	1,680	1,400	1,340	1,120	5.27 m
–1.5 m	kg	*3,750	*3,750	*2,990	2,480	1,670	1,390	1,610	1,340	4.62 m
–3.0 m	kg			*1,460	*1,460			*1,320	*1,320	3.22 m

SK75SR	SK75SR Arm: 2.06 m Bucket: Without Counterweight: 1,050 kg Shoe: 450 mm Dozer: Blade up										
	А	1.5 m		3.0 m		4.5 m		At max. reach			
В		1	<del></del>	1	<del></del>	-	<del></del>	4	<del></del>	Radius	
6.0 m	kg			*2,370	*2,370			*2,340	*2,340	3.24 m	
4.5 m	kg			*2,270	*2,270	1,900	1,620	1,710	1,450	4.74 m	
3.0 m	kg	*5,000	*5,000	*2,770	*2,770	1,810	1,530	1,270	1,070	5.46 m	
1.5 m	kg			3,130	2,530	1,640	1,370	1,100	920	5.70 m	
G.L.	kg			2,790	2,220	1,500	1,240	1,100	910	5.54 m	
–1.5 m	kg	*3,360	*3,360	2,730	2,170	1,460	1,200	1,290	1,060	4.94 m	
-3.0 m	kg	*2,480	*2,480	*1,880	*1,880			*1,450	*1,450	3.66 m	

SK75SR		Arm: 2.06 m	Bucket: Withou	t Counterweigh	unterweight: 1,050 kg + 300 kg Shoe: 450 mm Dozer: Blade up							
	А	1.5 m		3.0	3.0 m		4.5 m		At max. reach			
В		1	<del></del>	1	<del></del>	1	<del></del>	1	<b>—</b>	Radius		
6.0 m	kg			*2,370	*2,370			*2,340	*2,340	3.24 m		
4.5 m	kg			*2,270	*2,270	*2,000	1,770	1,870	1,590	4.74 m		
3.0 m	kg	*5,000	*5,000	*2,770	*2,770	1,980	1,690	1,400	1,190	5.46 m		
1.5 m	kg			3,440	2,800	1,810	1,520	1,230	1,040	5.70 m		
G.L.	kg			3,100	2,480	1,670	1,390	1,230	1,030	5.54 m		
–1.5 m	kg	*3,360	*3,360	3,040	2,430	1,630	1,350	1,440	1,200	4.94 m		
-3.0 m	kg	*2,480	*2,480	*1,880	*1,880			*1,450	*1,450	3.66 m		

- 1. Do not attempt to lift or hold any load that is greater than these lift capacities at their specified lift point radius and heights. Weight of all accessories must be deducted from the above lift capacities.
- 2. Lift capacities are based on machine standing on level, firm, and uniform ground. User must make allowance for job conditions such as soft or uneven ground, out of level conditions, side loads, sudden stopping of loads, hazardous conditions, experience of personnel, etc.
- 3. Arm top defined as lift point.
- 4. The above lift capacities are in compliance with ISO 10567. They do not exceed 87% of hydraulic lift capacity or 75% of tipping load. lift capacities marked with an asterisk(\*) are limited by hydraulic capacity rather than tipping load.
- 5. Operator should be fully acquainted with the Operator's and Maintenance Instructions before operating this machine. Rules for safe operation of equipment should be adhered to at all times.
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